Stability, complexity and diversity in random replicator models of ecology and evolutionary game theory

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Game theory

- 1944: von Neumann and Morgenstern 'Theory of games and economic behaviour'
- 1950s: John Nash, equilibrium concepts
- Nash equilibria seen as only viable outcomes of careful reasoning of rational players
- 1982: John Maynard Smith: 'Evolution and the theory of games', dynamics of a population of irrational players

Nobel prizes: 1994: J.C. Harsanyi, John Nash and R. Selten 2005: R. Aumann, Th. Schelling



- If is played by a (finite) number of players x, y, z, \ldots
- each of them has a set of strategies X, Y, Z, ...
- and each is paid a payoff depending on his choice of strategy and on the choice of the other players
- different players might have different strategy sets

symmetric versus asymmetric games

Matrix games

E.g. prisoners dilemma

payoff for player 1	2 co-	2 defects
	operates	
1 co-operates	4	0
1 defects	5	3

payoff for player 2	2 co-	2 defects
	operates	
1 co-operates	4	5
1 defects	0	3

Matrix games

Another example: rock-scissors-paper game

rock > scissors, scissors > paper but paper > rock

$$A = \left(\begin{array}{rrrr} 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \end{array} \right)$$

Matrix games

- these were all so-called symmetric games: only one type of player
- now an asymmetric game

Battle of the sexes:

- strategies for male: run or stay
- strategies for female: coy or fast
- successful raising of offspring: payoff G for each
- parental investment -C shared if male stays, otherwise borne entirely by female
- Iong engagement: cost E for both

Battle of the sexes

- successful raising of offspring: payoff G for each
- parental investment -C shared if male stays, otherwise borne entirely by female
- In long engagement: cost -E for both

payoff for male	female coy	female fast
male runs	0	G
male stays	$G - \frac{C}{2} - E$	$G - \frac{C}{2}$

payoff for female	male runs	male stays
female coy	0	$G - \frac{C}{2} - E$
female fast	G - C	$G - \frac{C}{2}$

Pure strategies

Assume player X has the choice between N pure strategies, labelled by

$$\vec{e_i}^x, i=1,\ldots,N$$

Then a mixed strategy corresponds to a vector

$$\vec{x} = (x_1, \dots, x_N), \qquad \sum_i x_i = 1$$

 x_i is the probability to play pure strategy $\vec{e_i}^x$.



Mixed strategies

I in general will have payoff matrices a_{ij} and b_{ij}

If player X plays mixed strategy \vec{x} and Y plays \vec{y} then

$$egin{aligned}
u^x(ec x,ec y) &=& \sum_{ij} x_i a_{ij} y_j \
u^y(ec x,ec y) &=& \sum_{ij} x_i b_{ij} y_j \end{aligned}$$

Nash Equilibria

A Nash equilibrium is a point $(\vec{x} *, \vec{y} *)$ such that no player has an incentive to change strategies unilaterally given the other player's choice of strategy:

- Image: $\vec{x} \star is the best choice for X given Y plays <math>\vec{y} \star is the best choice for X given Y plays <math>\vec{y} \star is the best choice for X given Y plays <math>\vec{y} \star is the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best choice for X given Y plays for the best for the best choice for X given Y plays for the best for the best choice for X given Y plays for the best for X given Y plays for the best for the best for the best for the best for X given Y plays for the best for the$
- Image: $\vec{y} \star is the best choice for Y given X plays <math>\vec{x} \star is$

$$u^x(ec{x}^{\,\star},ec{y}^{\,\star}) \;\; = \;\; \max_{ec{x}} \,
u^x(ec{x},ec{y}^{\,\star})$$

$$u^y(\vec{x}^{\star}, \vec{y}^{\star}) = \max_{\vec{y}} \nu^y(\vec{x}^{\star}, \vec{y})$$

replicator equations

$$\frac{d}{dt}x_i(t) = x_i(t)[f_i[x(t)] - f(t)]$$

- evolutionary game theory
- Iearning dynamics, e.g. acquisition of grammar
- chemical reactions
- interacting species, eco-systems

- \checkmark differential equations on a simplex S
- **population divided into** N types i = 1, ..., N with proportions x_i
- If the fitness of i: $f_i(t) = f_i[x_1(t), \dots, x_N(t)]$

The associated replicator equation reads

$$\frac{\dot{x_i}(t)}{x_i(t)} = f_i(t) - \overline{f}(t)$$

with $\overline{f}(t) = \sum_i x_i(t) f_i(t)$ the mean fitness

$$\dot{x}_i(t) = x_i(t) \left(f_i(t) - \overline{f}(t) \right)$$

- species fitter than the average prosper
- species less fit than the average decrease in concentration

•
$$\sum_{i} x_i = 1$$
 conserved in time

One population models

- \blacksquare only one type of players X
- e.g in the prisoner's dilemma or rock-scissors-paper game
- symmetric games

$$\dot{x}_i(t) = x_i(t) \left(f_i[x_1(t), \dots, x_N(t)) - \overline{f}(t) \right)$$

Multi-population models

- multiple types of players X, Y, Z,... taking different positons in the game
- e.g. male-female in battle of sexes, buyers-sellers in an economy
- asymmetric games

$$\dot{x_i}(t) = x_i(t) \left(f_i^x[y_1(t), \dots, y_N(t)] - \overline{f^x}(t) \right)$$

$$\dot{y_j}(t) = y_j(t) \left(f_j^y[x_1(t), \dots, x_M(t)] - \overline{f^y}(t) \right)$$

Fixed points:

$$0 = x_i \left(f_i - \overline{f} \right)$$

It turns out

stable fixed points are Nash equilibria

but Nash equilibria are not necessarily stable FP

Fixed point distribution

fraction ϕ of surviving species, $x_i > 0$

listribution ~ truncated Gaussian+ $(1 - \phi)\delta(x)$



$$\dot{x}_i(t) = x_i(t) \left(f_i[x_1(t), \dots, x_N(t)) - \overline{f}(t) \right)$$

games between two players

$$f_i[x_1,\ldots,x_N] = \sum_j J_{ij}x_j$$

games between p-players

$$f_i[x_1,\ldots,x_N] = \sum_{i_1,\ldots,i_{p-1}} J^i_{i_1,i_2,\ldots,i_{p-1}} x_{i_1} x_{i_2} \cdots x_{i_{p-1}}$$

study "all" matrix games 👄 random payoff matrices

$$\dot{x_i}(t) = x_i(t) \left(\sum_j J_{ij} x_j(t) - \overline{f}(t) \right)$$

vith

- J_{ij} Gaussian couplings, $\overline{J_{ij}^2} = 1/N$
- symmetry of couplings $\overline{J_{ij}J_{ji}} = \Gamma/N$
- diagonal elements $J_{ii} = -2u$
- u denotes 'co-operation pressure', drives the system into the simplex

$$\sum_i x_i(t) = N \qquad orall t$$

[Opper et al]

Co-operation pressure

[Peschel, Mende, The Prey-Predator model, Springer, 1985]



Fig. 89 The influence of λ upon source and sink behaviour

Literature

- statistical mechanics of large one-population systems with random couplings
 - Opper/Diederich PRA '89, PRL '92
 - Fontanari, De Oliveira PRL '00, PRE '01, PRL '02, EPJB '03, PRE '04 (all replica)
 - Biscari/Parisi J.Phys. A '95 (1RSB)
- bi-matrix games
 - Berg/Engel PRL '99
 - Berg/Weigt Europhys. Lett '99
 - Berg PRE '00

Random replicator equations

$$\dot{x}_i(t) = x_i(t) \left(\sum_j J_{ij} x_j(t) - \overline{f}(t) \right)$$

with random Gaussian couplings

 \bigstar can be solved with techniques from spin glass physics in the thermodynamic limit $\,N\to\infty\,$

† path-integrals, dynamical generating functionals

<u>result</u>: stochastic process for a representative strategy/species

fixed point ansatz gives closed equations for persistent OP

[Opper et al]

Generating functional analysis

Study this with generating functionals.

- advantange over replica:
 - no Lyapunov function required
 - so that GFA can be used also for asymmetric couplings
 - replica theory only for symmetric couplings
- closed laws for dynamical order parameters:
 - correlation function $C(t,t') = N^{-1} \sum_i \overline{\langle x_i(t) x_i(t') \rangle}$
 - response function $G(t,t') = N^{-1} \sum_{i} \overline{\left\langle \frac{\partial x_i(t)}{\partial h(t')} \right\rangle}$
 - Lagrange multiplier $\overline{f}(t)$

Generating functional analysis

effective species process

$$\dot{x}(t) = x(t) \left(-2ux(t) - \Gamma \frac{p(p-1)}{2} \int_{t_0}^t dt' G(t,t') C(t,t')^{p-2} x(t') + \eta(t) - \overline{f}(t) + h(t) \right)$$

self-consistent problem

$$C(t,t') = \left\langle x(t)x(t') \right\rangle_{\star}, \quad G(t,t') = \left\langle \frac{\partial x(t)}{\partial h(t')} \right\rangle_{\star}, \quad \left\langle x(t) \right\rangle_{\star} = 1$$

$$\left\langle \eta(t)\eta(t')\right\rangle_{\star} = \frac{p}{2}C(t,t')^{p-1}$$

• retarded interaction $\int_{t_0}^t dt' G(t,t') C^{p-2}(t,t') x(t')$



Ergodicity breaking - sensitivity to initial conditions



Typical trajectories



p = 3

Find ergodicity breaking also for p = 3:



But if p = 3 but quadratic self-interaction find collapse of extensivity

 $\phi \sim N^{\delta}$



Bi-matrix games

Payoff matrices a_{ij} , b_{ij} with

$$\overline{a_{ij}^2} = \overline{b_{ij}^2} = 1/N, \qquad \overline{a_{ij}b_{ji}} = \Gamma/N$$

Berg/Weigt [Europhys. Lett. 48 129 (1999)]:



Bi-matrix games:

two-population random replicators

$$egin{array}{rcl} \dot{x_i} &=& x_i(t) \left(-2 u x_i + \sum_j a_{ij} y_j -
u^x
ight) \ \dot{y_j} &=& y_j(t) \left(-2 u y_j + \sum_i b_{ij} x_i -
u^y
ight) \end{array}$$

generating functionals lead to two coupled effective processes

$$\dot{x} = x(t) \left(-2ux + \Gamma \int dt' G_y(t,t') x(t') - \nu^x - \eta^x(t) \right)$$
$$\dot{y} = y(t) \left(-2uy + \Gamma \int dt' G_x(t,t') y(t') - \nu^y - \eta^y(t) \right)$$

with

$$\left\langle \eta^{x}(t)\eta^{x}(t')\right\rangle = \left\langle y(t)y(t')\right\rangle \qquad \left\langle \eta^{y}(t)\eta^{y}(t')\right\rangle = \left\langle x(t)x(t')\right\rangle$$

Dynamic instability and number of Nash equilibria



dynamic instability coincides with onset of exponential number of NE

Counting the Nash Equilibria



Statistical mechanics of simple model eco-systems work with Yoshimi Yoshino and Kei Tokita (Osaka)

J. Stat. Mech. (2007) P09003

Phys. Rev. E (2008) to appear

The model

two 'trophic levels':



Model definitions

two 'trophic levels':

 $i = 1, \ldots, N$ N species α $\mu = 1, \ldots, P$ P resources fitness of $f_i = \sum J_{ij} x_j + \sum \xi_i^{\mu} A^{\mu}$ species i μ direct interaction use of resources between species abundance of $A^{\mu}(t) = A^{\mu}_{0} - \sum \dot{\xi}^{\mu}_{i} x_{i}(t)$ resource μ

Model definitions



[see also A De Martino and M Marsili J. Phys. A 39 R465 (2007)]

E.g. phase diagram in dependence of number of resources and their variability



Use of resources





many resources

Robustness of the model: distribution of species-resource couplings



Species abundance distributions in replicator models



[Yoshino, Galla, Tokita, PRE (2008) to appear] [Tokita, PRL 2004]

Conclusions

 used techniques from statistical physics used to study replicator systems with random interaction matrices

transition between ergodic-stable and non-ergodic-unstable phase

order parameters computable in stable regime

extension to simple model-eco system with two trophic levels

phases with perfect exploitation of resources